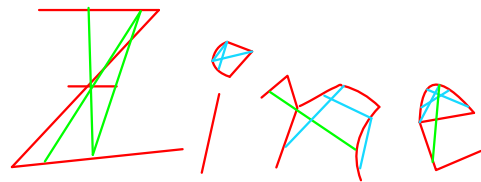
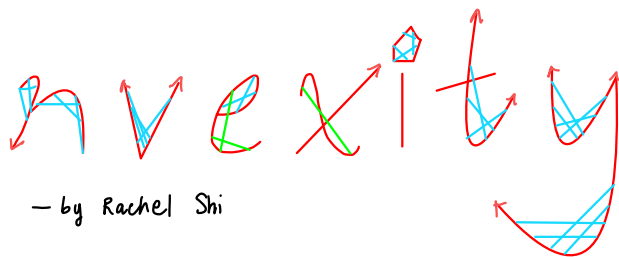
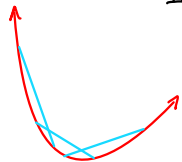


Intro to



- by Rachel Shi

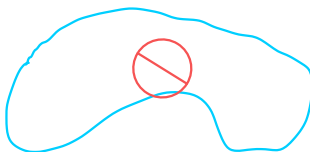
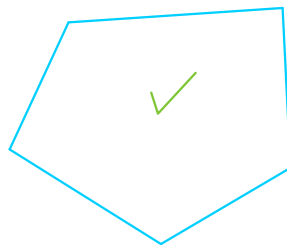
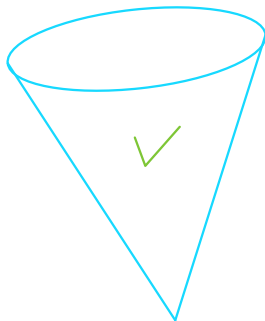


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What is a convex cone?



a set C is **convex** if for any two elements $x, y \in C$,

the element:

$$z = \alpha x + (1-\alpha)y \in C$$

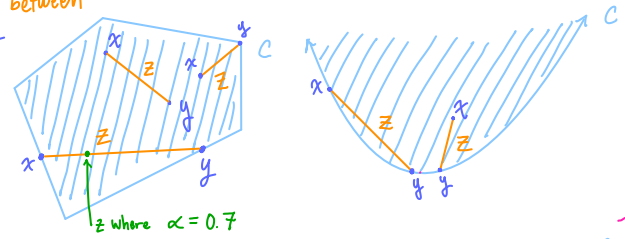
↑
in

notice that all such points z form a chord between points x and y

$$\forall \alpha \in [0, 1]$$

↑
in

for all α between 0 and 1 (including 0 and 1)



examples of convex sets

In other words, C is convex if any line segment between two elements in C is also in C .

a set C is a **cone** if $x \in C$,

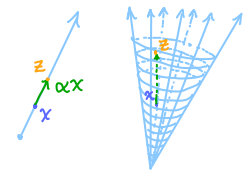
$$\text{then } z = \alpha x \in C$$

↑
in

$$\forall \alpha \geq 0$$

↑
in

for all α that is not negative



examples of cones

combining these two ideas, a **convex cone** is a set C where if $x, y \in C$

$$\text{then } z = \alpha_x x + \alpha_y y \in C$$

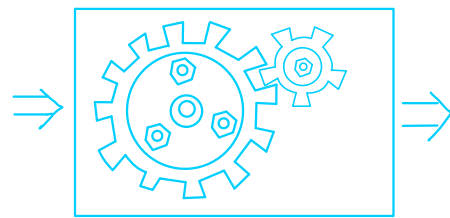
↑
in

$$\forall \alpha_x, \alpha_y \geq 0$$

↑
in

for all α_x and α_y are both greater than 0

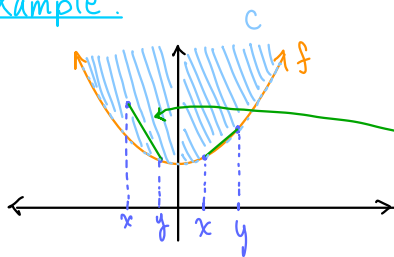
Convex Functions



given a convex set, C , a function on C , $f: C \rightarrow \mathbb{R}$,
 f is convex if $\forall x, y \in C$ and $\forall \alpha \in [0, 1]$:

$$f(\alpha x + (1-\alpha)y) \leq \alpha f(x) + (1-\alpha)f(y)$$

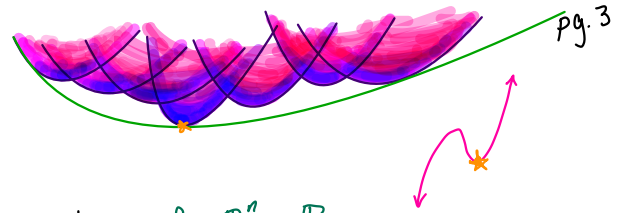
example:



intuitively, this means that for any 2 points in C ,
 the line segment between them lies

✎ ABOVE ✎ the graph of convex function f .

General Optimization



the general form of a mathematical optimization problem is:

problem { minimize/maximize $f_0(x)$ ← an objective function! where $f_0: \mathbb{R}^n \rightarrow \mathbb{R}$
subject to $f_i(x) \leq b_i$ ← constraint functions! where $f_i: \mathbb{R}^n \rightarrow \mathbb{R}$
for $i=1, \dots, m$
 x (a vector) is our optimization variable!

solution { we usually call an optimal value of x , x^*
which is the solution to our problem ← called "x-star"



Known as LP! → linear programming: a special case of the general optimization problem

constraints { where all constraint functions are linear
↳ this means that each of the functions f_0, \dots, f_m satisfy:

$$f_i(\alpha x + \beta y) = \alpha f_i(x) + \beta f_i(y)$$

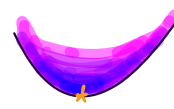
linear programs are usually written in the form:

$$\begin{aligned} &\text{maximize} && c^T x \\ &\text{subject to} && Ax \leq b \rightarrow \text{where } A \text{ is a matrix} \\ &\text{and} && x \geq 0 \quad \text{and } b \text{ is a vector} \end{aligned}$$



ya like jazz?

Convex Optimization



Like linear programming, convex optimization is a special case of the general optimization problem,

constraints {

where all constraint functions are convex

↳ this means that each of the functions f_0, \dots, f_m satisfy:

$$f_i(\alpha x + \beta y) \leq \alpha f_i(x) + \beta f_i(y)$$

Comparing this to linear programming where

constraint functions are linear

↳ this means that each of the functions f_0, \dots, f_m satisfy:

$$f_i(\alpha x + \beta y) = \alpha f_i(x) + \beta f_i(y)$$

we see that linear programming is a special case of convex optimization

